

Section 3.2

Vector Equations and Spans

Outline of Section 3.2

- Learn the equivalences:

vector equations \leftrightarrow augmented matrices \leftrightarrow linear systems

- Learn the definition of **span**
- Learn the relationship between spans and consistency

Linear combinations, vector equations, and linear systems

We just saw the following question:

Is $\begin{pmatrix} 8 \\ 16 \\ 3 \end{pmatrix}$ a linear combination of $\begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix}$ and $\begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix}$?

And saw it was the same as a vector equation:

$$c_1 \begin{pmatrix} 1 \\ 2 \\ 6 \end{pmatrix} + c_2 \begin{pmatrix} -1 \\ -2 \\ -1 \end{pmatrix} = \begin{pmatrix} 8 \\ 16 \\ 3 \end{pmatrix}$$

which is the same as the system of linear equations:

$$c_1 - c_2 = 8$$

$$2c_1 - 2c_2 = 16$$

$$6c_1 - c_2 = 3$$

which we solve by row reducing, and we get $(c_1, c_2) = (-1, -9)$.

Linear combinations, vector equations, and linear systems

In general, asking:

Is b a linear combination of v_1, \dots, v_k ?

is the same as asking if the vector equation

$$c_1 v_1 + \dots + c_k v_k = b$$

is consistent, which is the same as asking if the system of linear equations corresponding to the augmented matrix

$$\left(\begin{array}{c|c|c|c|c|c} | & | & & | & | & | \\ v_1 & v_2 & \cdots & v_k & & b \\ | & | & & | & | & | \end{array} \right),$$

is consistent.

Compare with the previous slide! Make sure you are comfortable going back and forth between the specific case (last slide) and the general case (this slide).

Span

Essential vocabulary word!

$\text{Span}\{v_1, v_2, \dots, v_k\} = \{c_1 v_1 + c_2 v_2 + \dots + c_k v_k \mid c_i \text{ in } \mathbb{R}\} \leftarrow (\text{set builder notation})$
= the set of all linear combinations of vectors v_1, v_2, \dots, v_k
= plane through the origin and v_1, v_2, \dots, v_k .

What are the possibilities for the span of two vectors in \mathbb{R}^2 ?

▶ Demo

What are the possibilities for the span of three vectors in \mathbb{R}^3 ?

▶ Demo

Conclusion: Spans are planes (of some dimension) through the origin, and the dimension of the plane is **at most** the number of vectors you started with and is **at most** the dimension of the space they're in.

Span

Essential vocabulary word!

$\text{Span}\{v_1, v_2, \dots, v_k\} = \{c_1v_1 + c_2v_2 + \dots + c_kv_k \mid c_i \text{ in } \mathbb{R}\}$
= the set of all linear combinations of vectors v_1, v_2, \dots, v_k
= plane through the origin and v_1, v_2, \dots, v_k .

Four ways of saying the same thing:

- b is in $\text{Span}\{v_1, v_2, \dots, v_k\}$
- b is a linear combination of v_1, \dots, v_k
- the vector equation $c_1v_1 + \dots + c_kv_k = b$ has a solution
- the system of linear equations corresponding to

$$\left(\begin{array}{c|c|c|c|c} | & | & \cdots & | & | \\ v_1 & v_2 & & v_k & b \\ | & | & & | & | \end{array} \right),$$

is consistent.

Summary of Section 3.2

- Checking if a linear system is consistent is the same as asking if the column vector on the end of an augmented matrix is in the span of the other column vectors.
- Spans are planes, and the dimension of the plane is **at most** the number of vectors you started with.