

Announcements: October 15

- Midterm 2 **Friday** in recitation, §3.5–4.4
- **WeBWoRk** due **Wednesday**
- Supplemental problems and Practice exam on web site
- My office hours **Wed 2-3** and Friday 9:30-10:30 in Skiles 234
- Review sessions
 - ▶ Talha Wed 6-7:30 Skiles 257
 - ▶ Talha Thu 6-7:30 Skiles 257
 - ▶ Arjun Thu 8-9:30 Skiles 256
- TA office hours
 - ▶ Arjun Wed 3-4 Skiles 230
 - ▶ Talha Tue/Thu 11-12 Clough 248
 - ▶ Athreya Tue 3-4 Skiles 230
 - ▶ Olivia Thu 3-4 Skiles 230
 - ▶ James Fri 12-1 Skiles 230
 - ▶ Jesse Wed 9:30-10:30 Skiles 230
 - ▶ Vajraang Thu 9:30-10:30 Skiles 230
 - ▶ Hamed Thu 11:15-12, 1:45-2:45, 3-4:15 Clough 280
- Math Lab Monday-Thursday 11:15-5:15 Clough 280
- PLUS Sessions
 - ▶ Tue/Thu 6-7 Clough 280
 - ▶ Mon/Wed 7-8 Clough 123

Review for Midterm 2

Summary of Section 3.5

- A set of vectors $\{v_1, \dots, v_k\}$ in \mathbb{R}^n is **linearly independent** if the vector equation

$$c_1v_1 + c_2v_2 + \dots + c_kv_k = 0$$

has only the trivial solution. It is **linearly dependent** otherwise.

- The cols of A are linearly independent
 - $\Leftrightarrow Ax = 0$ has only the trivial solution.
 - $\Leftrightarrow A$ has a pivot in each column
- The number of pivots of A equals the dimension of the span of the columns of A
- The set $\{v_1, v_2, \dots, v_k\}$ is linearly dependent if and only if some v_i lies in the span of v_1, \dots, v_{i-1} .

I have an 4×3 matrix A and a vector b in \mathbb{R}^3 , and $Ax = b$ is inconsistent. Are the columns of A linearly dependent?

Section 3.6 Summary

- A **subspace** of \mathbb{R}^n is a subset V with:
 1. The zero vector is in V .
 2. If u and v are in V , then $u + v$ is also in V .
 3. If u is in V and c is in \mathbb{R} , then $cu \in V$.
 - Two important subspaces: **Nul(A)** and **Col(A)**
 - Find a spanning set for Nul(A) by solving $Ax = 0$ in vector parametric form
 - Find a spanning set for Col(A) by taking pivot columns of A (not reduced A)
 - Four things are the same: subspaces, spans, planes through 0, null spaces
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Let V be the subset of \mathbb{R}^3 consisting of the x -axis, the y -axis, and the z -axis. Which properties of a subspace does V fail?

Find a spanning set for the plane in \mathbb{R}^3 defined by $x + y - 2z = 0$.

Section 3.7 Summary

- A **basis** for a subspace V is a set of vectors $\{v_1, v_2, \dots, v_k\}$ such that
 1. $V = \text{Span}\{v_1, \dots, v_k\}$
 2. v_1, \dots, v_k are linearly independent
 - The number of vectors in a basis for a subspace is the dimension.
 - Find a basis for $\text{Nul}(A)$ by solving $Ax = 0$ in vector parametric form
 - Find a basis for $\text{Col}(A)$ by taking pivot columns of A (not reduced A)
 - **Basis Theorem**. Suppose V is a k -dimensional subspace of \mathbb{R}^n . Then
 - ▶ Any k linearly independent vectors in V form a basis for V .
 - ▶ Any k vectors in V that span V form a basis.
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Find a basis $\{u, v, w\}$ for \mathbb{R}^3 where no vector has a zero entry.

Section 3.9 Summary

- Rank-Nullity Theorem. $\text{rank}(A) + \dim \text{Nul}(A) = \#\text{cols}(A)$
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Let A be an 4×6 nonzero matrix and suppose the columns of A are all the same. What is $\dim \text{Nul}(A)$?

Section 4.1 Summary

- If A is an $m \times n$ matrix, then the associated matrix transformation T is given by $T(v) = Av$. This is a function with domain \mathbb{R}^n and codomain \mathbb{R}^m and range $\text{Col}(A)$.
 - If A is $n \times n$ then T does something to \mathbb{R}^n ; basic examples: reflection, projection, scaling, shear, rotation
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Find a matrix A so that the range of the matrix transformation $T(v) = Av$ is the line $y = 2x$ in \mathbb{R}^2 .

Summary of Section 4.2

- $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **one-to-one** if each b in \mathbb{R}^m is the output for at most one v in \mathbb{R}^n .
- **Theorem.** Suppose $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a matrix transformation with matrix A . Then the following are all equivalent:
 - ▶ T is one-to-one
 - ▶ the columns of A are
 - ▶ $Ax = 0$ has
 - ▶ A has a pivot
 - ▶ the range has dimension n
- $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **onto** if the range of T equals the codomain \mathbb{R}^m , that is, each b in \mathbb{R}^m is the output for at least one input v in \mathbb{R}^n .
- **Theorem.** Suppose $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a matrix transformation with matrix A . Then the following are all equivalent:
 - ▶ T is onto
 - ▶ the columns of A
 - ▶ A has a pivot
 - ▶ $Ax = b$ is consistent
 - ▶ the range of T has dimension m

Let A be an 5×5 matrix. Suppose that $\dim \text{Nul}(A) = 0$. Must it be true that $Ax = e_1$ is consistent?

Summary of 4.3

- A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **linear** if
 - ▶ $T(u + v) = T(u) + T(v)$ for all u, v in \mathbb{R}^n .
 - ▶ $T(cv) = cT(v)$ for all $v \in \mathbb{R}^n$ and c in \mathbb{R} .
 - **Theorem.** Every linear transformation is a matrix transformation (and vice versa).
 - The standard matrix for a linear transformation has its i th column equal to $T(e_i)$.
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Find the standard matrix for the linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that reflects over the line $y = -x$.

Summary of Section 4.4

- Composition: $(T \circ U)(v) = T(U(v))$ (do U then T)
- Matrix multiplication: $(AB)_{ij} = r_i \cdot b_j$
- Matrix multiplication: the i th column of AB is $A(b_i)$
- The standard matrix for a composition of linear transformations is the product of the standard matrices.
- **Warning!**
 - ▶ AB is not always equal to BA
 - ▶ $AB = AC$ does not mean that $B = C$
 - ▶ $AB = 0$ does not mean that A or B is 0

Find a 2×2 matrix A , not equal to I or 0 , with $A^4 = I$.

Important terms

- linearly independent
- subspace
- column space
- null space
- basis
- dimension
- matrix transformation
- one-to-one
- onto
- linear transformation
- composition

Good luck!