Announcements Sep 20

- Masks \rightsquigarrow extra credit.
- *•* WeBWorK 2.3 & 2.4 due Tuesday nite
- *•* Midterm Wednesday 8–9:15p on Teams in your Studio channel, udio-channel, $\mu p \nrightarrow 2.4$
- *•* No quiz Friday
- *•* Use Piazza for general questions
- Office hrs: Tue 4-5 Teams $+$ Thu 1-2 Skiles courtyard/Teams $+$ Pop-ups
- **Many TA office hours listed on Canvas**
- *•* Section M web site: Google "Dan Margalit math", click on 1553
	- \blacktriangleright future blank slides, past lecture slides, old quizzes/exams, advice
- *•* Tutoring: <http://tutoring.gatech.edu/tutoring>
- *•* PLUS sessions: <http://tutoring.gatech.edu/plus-sessions>
- *•* Math Lab: <http://tutoring.gatech.edu/drop-tutoring-help-desks>

- *•* Counseling center: <https://counseling.gatech.edu>
- *•* You can do it!

Section 2.4

Solution Sets

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Homogeneous vs. Nonhomogeneous Systems

Key realization. Set of solutions to $Ax = b$ obtained by taking one solution and adding all possible solutions to $Ax = 0$.

 $Ax = 0$ solutions $\leadsto Ax = b$ solutions

 $x_k v_k + \cdots + x_n v_n \rightsquigarrow p + x_k v_k + \cdots + x_n v_n$

So: set of solutions to $Ax = b$ is parallel to the set of solutions to $Ax = 0$. It is a translate of a plane through the origin. (Again, we are using geometry to understand algebra!)

So by understanding $Ax = 0$ we gain understanding of $Ax = b$ for all b. This gives structure to the set of equations $Ax = b$ for all b.

Parametric Vector Forms for Solutions h_0 mog. Nonhomogeneous case Find the parametric vector forms for $\begin{pmatrix} 1 & -3 \ 2 & 6 \end{pmatrix}$ ◆ ✓ *x* ◆ $\begin{pmatrix} 0 \\ 0 \end{pmatrix}$ ◆ = 2 -6 *y* 0 $\begin{pmatrix} 1 & -3 \\ 2 & -6 \end{pmatrix}$ \rightarrow $\begin{pmatrix} 1 & -3 \\ 0 & 0 \end{pmatrix}$ \rightarrow $\begin{pmatrix} x_1 & -3x_2 \\ x_2 & -x_2 \end{pmatrix}$ \rightarrow $\begin{pmatrix} 3 \\ 1 \end{pmatrix}$ $\int_{\alpha,+}^{\alpha+\alpha}$ param non-homog form form ...and $\begin{pmatrix} 1 & -3 \\ 2 & 6 \end{pmatrix}$ ◆ ✓ *x* ◆ $\begin{pmatrix} 3 \end{pmatrix}$ ◆ = . $2 -6$ *y* 6 $3 + 5$ $\begin{array}{c} 1 & -5 & 5 \\ 2 & -6 & 6 \end{array} \longrightarrow \begin{array}{c} 1 & 0 \\ 0 & 0 \end{array}$ x_2 = x_2 $\begin{array}{ccc}\n\text{Span } \{1\} \times 0 & \text{solrs} \\
\hline\n\end{array}\n\qquad\n\begin{array}{ccc}\nA_{X}=0 & \text{solrs} \\
A_{X}=(\frac{3}{6}) & \text{colrs} \\
\end{array}\n\qquad\n\begin{array}{ccc}\n\text{Span } d & \text{cols} \\
\text{Gls } d & \text{cols} \\
\end{array}\n\qquad\n\begin{array}{ccc}\n\text{Span } d & \text{cols} \\
\end{array}\n\qquad\n\begin{array}{ccc}\n\text{Span } d & \text{cols} \\
\end{array}\n\qquad\n\begin{array}{ccc}\n\text{Cone,$ Ax ^Osons sohs $Ax = b$ consist. $Spin(2)$ KOD KAPD KIDD KIDD I DA G

Solving matrix equations

The matrix equation

$$
\left(\underbrace{\begin{pmatrix} 0 & 6 & 8 \\ \sqrt{2} & 0 & 0 \\ 0 & \sqrt{1/2} & 0 \end{pmatrix}}_{\text{has only the trivial solution.}} \begin{pmatrix} f \\ s \\ t \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}
$$

What does this mean about the matrix equation

$$
\begin{pmatrix} 0 & 6 & 8 \ 1/2 & 0 & 0 \ 0 & 1/2 & 0 \end{pmatrix} \begin{pmatrix} f \ s \ t \end{pmatrix} = \begin{pmatrix} 20 \ 1 \ 1 \end{pmatrix}?
$$

\nOne Solution
\n
$$
\begin{pmatrix} 6 & 8 \ 1 & 1/2 \ 0 & 1/2 \end{pmatrix} = \begin{pmatrix} 4 & 1 \ 1 & 1/2 \ 1 & 1/2 \end{pmatrix}?
$$

\nWhat does this mean about rabbits?

Section 2.5 Linear Independence

Section 2.5 Outline

• Understand what is means for a set of vectors to be linearly independent

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• Understand how to check if a set of vectors is linearly independent

The idea of linear independence: a collection of vectors v_1, \ldots, v_k is linearly independent if they are all pointing in truly different directions. Precisely, this means that none of the *vⁱ* is in the span of the others.

For example, $(1,0,0)$, $(0,1,0)$ and $(0,0,1)$ are linearly independent.

equations is: What is the smallest number of vectors needed in the parametric solution to a linear system? We need linear independence to answer this question. See the last slide in this section.

A set of vectors $\{v_1, \ldots, v_k\}$ in \mathbb{R}^n is linearly independent if the vector equation

 $x_1v_1 + x_2v_2 + \cdots + x_kv_k = 0$

 $\sqrt{2}$

 ∞

has only the trivial solution. It is linearly dependent otherwise.

$$
\frac{1}{2} \int \frac{1
$$

So, linearly dependent means there are x_1, x_2, \ldots, x_k not all zero so that

 $x_1v_1 + x_2v_2 + \cdots + x_kv_k = 0$

This is a *linear dependence* relation.

$$
-1\begin{pmatrix}1\\0\\0\end{pmatrix} + -1\begin{pmatrix}0\\1\\0\end{pmatrix} + \frac{1}{\sqrt{2\pi}}\begin{pmatrix}1\\1\\0\end{pmatrix} = \begin{pmatrix}0\\0\\0\end{pmatrix}
$$

A set of vectors $\{v_1, \ldots, v_k\}$ in \mathbb{R}^n is linearly independent if the vector equation

$$
x_1v_1+x_2v_2+\cdots+x_kv_k=0
$$

homogen

 $A 4x3$ matrix

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 is 3 vectors

in \mathbb{R}^n . Those can be

has only the trivial solution.

no freevars

Fact. The columns of *A* are linearly independent $\Leftrightarrow Ax = 0$ has only the trivial solution. \Leftrightarrow *A* has a pivot in each column

Why?

$$
\mathcal{A} = \left(\begin{array}{ccc} 1 & 1 & 1 \\ \sqrt{1} & \sqrt{2} & \sqrt{3} \\ 1 & 1 & 1 \end{array}\right)
$$

A 3×4 matrix can't have a pivot
in each col so....
4 vectors in
$$
\mathbb{R}^3
$$
 can't be independent

Is
$$
\left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix} \right\}
$$
 linearly independent?
\n $\left\{ \begin{pmatrix} 1 & 1 & 3 \\ 1 & -1 & 1 \\ 1 & 2 & 4 \end{pmatrix} \right\} \rightsquigarrow \left\{ \begin{pmatrix} 1 & 1 & 3 \\ 0 & -2 & -2 \\ 0 & 1 & 1 \end{pmatrix} \right\} \rightsquigarrow \left\{ \begin{pmatrix} 1 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right\}$
\nIs $\left\{ \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix} \right\}$ linearly independent?
\n $\left\{ \begin{pmatrix} 1 & 3 \\ 1 & -1 & 1 \\ -2 & 2 & 4 \end{pmatrix} \right\} \longmapsto \left\{ \begin{pmatrix} 1 & 1 & 3 \\ 0 & -2 & -2 \\ 0 & 4 & 10 \end{pmatrix} \right\} \longmapsto \left\{ \begin{pmatrix} 1 & 3 \\ 0 & -2 & 2 \\ 0 & 6 & 6 \end{pmatrix} \right\}$

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When is *{v}* is linearly dependent?

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When is $\{v_1, v_2\}$ is linearly dependent?

 $V_1 + V_2$

When is the set $\{v_1, v_2, v_3\}$ linearly dependent?

▶ [Demo](http://textbooks.math.gatech.edu/ila/demos/spans.html?captions=indep&v1=2,-1,1&v2=1,0,-1&v3=.5,-.5,1&labels=v,w,x&range=5)

When V = Zero vector.

When V_1 is a multiple of V_2 for vice version or: they lie on same line or: one in span example $\left(\frac{1}{4}\right) 2 \cdot \left(\frac{3}{1}\right) - 1 \left(\frac{6}{14}\right) = 0$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right) = O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}\right)$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right) = O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}\right)$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right) = O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}\right)$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right) = O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}\right)$ $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \right) = O\left(\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}\right)$

Fact. The set $\{v_1, v_2, \ldots, v_k\}$ is linearly independent if and only if they span a *k*-dimensional plane. (algebra \leftrightarrow geometry)

Fact. The set $\{v_1, v_2, \ldots, v_k\}$ is linearly dependent if and only if we can remove a vector from the set without changing (the dimension of) the span.

Fact. The set $\{v_1, v_2, \ldots, v_k\}$ is linearly dependent if and only if some v_i lies in the span of v_1, \ldots, v_{i-1} .

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Span and Linear Independence

$$
\text{Is } \left\{ \left(\begin{array}{c} 5 \\ 7 \\ 0 \end{array} \right), \left(\begin{array}{c} -5 \\ 7 \\ 0 \end{array} \right), \left(\begin{array}{c} 3 \\ 1 \\ 4 \end{array} \right) \right\} \text{ linearly independent?}
$$

Try using the last fact: the set $\{v_1, v_2, \ldots, v_k\}$ is linearly dependent if and only if some v_i lies in the span of v_1, \ldots, v_{i-1} .

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\n- \n
$$
\begin{pmatrix} 5 \\ 7 \\ 6 \end{pmatrix}
$$
 not in span of previous vectors\n $\begin{pmatrix} -5 \\ 7 \\ 1 \end{pmatrix}$ not in span of $\begin{pmatrix} 5 \\ 7 \\ 0 \end{pmatrix}$ (not a multiple)\n
\n- \n $\begin{pmatrix} 3 \\ 1 \\ 4 \end{pmatrix}$ not in span of $\begin{pmatrix} 5 \\ 7 \\ 0 \end{pmatrix}$, $\begin{pmatrix} -5 \\ 7 \\ 0 \end{pmatrix}$ because of the 4.\n
\n- \n $\begin{pmatrix} 3 \\ 4 \end{pmatrix}$ not in $\begin{pmatrix} 5 \\ 7 \\ 0 \end{pmatrix}$, $\begin{pmatrix} -5 \\ 7 \\ 0 \end{pmatrix}$ be case of the 4.\n
\n

Linear independence and free variables

Theorem. Let v_1, \ldots, v_k be vectors in \mathbb{R}^n and consider the vector equation

 $x_1v_1 + \cdots + x_kv_k = 0.$

The set of vectors corresponding to non-free variables are linearly independent.

So, given a bunch of vectors v_1, \ldots, v_k , if you want to find a collection of v_i that are linearly independent, you put them in the columns of a matrix, row reduce, find the pivots, and then take the original *vⁱ* corresponding to those columns.

Example. Try this with (1*,* 1*,* 1), (2*,* 2*,* 2), and (1*,* 2*,* 3).

Linear independence and coordinates

Fact. If v_1, \ldots, v_k are linearly independent vectors then we can write each element of

Span*{v*1*,...,vk}*

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in exactly one way as a linear combination of v_1, \ldots, v_k .

Span and Linear Independence

Two More Facts

Fact 1. Say v_1, \ldots, v_k are in \mathbb{R}^n . If $k > n$, then $\{v_1, \ldots, v_k\}$ is linearly dependent.

Fact 2. If one of v_1, \ldots, v_k is 0, then $\{v_1, \ldots, v_k\}$ is linearly dependent.

Parametric vector form and linear independence

Poll

Say you find the parametric vector form for a homogeneous system of linear equations, and you find that the set of solutions is the span of certain vectors. Then those vectors are...

- 1. always linearly independent
- 2. sometimes linearly independent
- 3. never linearly independent

Example. In Section 2.4 we solved the matrix equation $Ax = 0$ where

$$
A = \begin{pmatrix} 1 & 2 & 0 & -1 \\ -2 & -3 & 4 & 5 \\ 2 & 4 & 0 & -2 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & -8 & -7 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{pmatrix}
$$

In parametric vector form, the solution is:

$$
x_3 \left(\begin{array}{c} 8 \\ -4 \\ 1 \\ 0 \end{array}\right) + x_4 \left(\begin{array}{c} 7 \\ -3 \\ 0 \\ 1 \end{array}\right) \qquad \qquad \text{for all } 3 \leq r \leq 3 \quad \text{for all } r \leq r \quad \text{if } r \geq 3 \quad \text{if } r \geq
$$

Parametric Vector Forms and Linear Independence

In Section 2.4 we solved the matrix equation $Ax = 0$ where

$$
A = \left(\begin{array}{rrr} 1 & 2 & 0 & -1 \\ -2 & -3 & 4 & 5 \\ 2 & 4 & 0 & -2 \end{array}\right) \rightsquigarrow \left(\begin{array}{rrr} 1 & 0 & -8 & -7 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{array}\right)
$$

In parametric vector form, the solution is:

$$
x_3 \left(\begin{array}{c} 8 \\ -4 \\ 1 \\ 0 \end{array} \right) + x_4 \left(\begin{array}{c} 7 \\ -3 \\ 0 \\ 1 \end{array} \right)
$$

The two vectors that appear are linearly independent (why?). This means that we can't write the solution with fewer than two vectors (why?). This also means that this way of writing the solution set is efficient: for each solution, there is only one choice of x_3 and x_4 that gives that solution.

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Summary of Section 2.5

• A set of vectors $\{v_1, \ldots, v_k\}$ in \mathbb{R}^n is linearly independent if the vector equation

 $x_1v_1 + x_2v_2 + \cdots + x_kv_k = 0$

has only the trivial solution. It is linearly dependent otherwise.

- *•* The cols of *A* are linearly independent
	- $\Leftrightarrow Ax = 0$ has only the trivial solution.
	- \Leftrightarrow *A* has a pivot in each column
- *•* The number of pivots of *A* equals the dimension of the span of the columns of *A*
- The set $\{v_1, \ldots, v_k\}$ is linearly independent \Leftrightarrow they span a *k*-dimensional plane
- The set $\{v_1,\ldots,v_k\}$ is linearly dependent \Leftrightarrow some v_i lies in the span of $v_1, \ldots, v_{i-1}.$
- *•* To find a collection of linearly independent vectors among the $\{v_1, \ldots, v_k\}$, row reduce and take the (original) v_i corresponding to pivots.

Typical exam questions

- *•* State the definition of linear independence.
- *Always/sometimes/never.* A collection of 99 vectors in \mathbb{R}^{100} is linearly dependent.
- *Always/sometimes/never.* A collection of 100 vectors in \mathbb{R}^{99} is linearly dependent.
- *•* Find all values of *h* so that the following vectors are linearly independent:

$$
\left\{ \left(\begin{array}{c} 5 \\ 7 \\ 1 \end{array} \right), \left(\begin{array}{c} -5 \\ 7 \\ 0 \end{array} \right), \left(\begin{array}{c} 10 \\ 0 \\ h \end{array} \right) \right\}
$$

- *• True/false.* If *A* has a pivot in each column, then the rows of *A* are linearly independent.
- *True/false.* If u and v are vectors in \mathbb{R}^5 then $\{u, v, \sqrt{2}u \pi v\}$ is linearly independent.
- *•* If you have a set of linearly independent vectors, and their span is a line, how many vectors are in the set?