

Section 3.3

Linear Transformations

Section 3.3 Outline

- Understand the definition of a linear transformation
- Linear transformations are the same as matrix transformations
- Find the matrix for a linear transformation

Linear transformations

A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear transformation** if

- $T(u + v) = T(u) + T(v)$ for all u, v in \mathbb{R}^n .
- $T(cv) = cT(v)$ for all v in \mathbb{R}^n and c in \mathbb{R} .

First examples: matrix transformations.

Linear transformations

A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear transformation** if

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- $T(cv) = cT(v)$ for all v in \mathbb{R}^n and c in \mathbb{R} .

Notice that $T(0) = 0$. *Why?*

We have the standard basis vectors for \mathbb{R}^n :

$$e_1 = (1, 0, 0, \dots, 0)$$

$$e_2 = (0, 1, 0, \dots, 0)$$

\vdots

If we know $T(e_1), \dots, T(e_n)$, then we know every $T(v)$. *Why?*

In engineering, this is called the principle of superposition.

Which are linear transformations?

And why?

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + y \\ y \\ x - y \end{pmatrix}$$

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + y + 1 \\ y \\ x - y \end{pmatrix}$$

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} xy \\ y \\ x - y \end{pmatrix}$$

A function $\mathbb{R}^n \rightarrow \mathbb{R}^m$ is linear exactly when the coordinates are linear (linear combinations of the variables, no constant terms).

Linear transformations

Which properties of a linear transformation fail for this function $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$?

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ |y| \end{pmatrix}$$

Linear transformations are matrix transformations

Theorem. Every linear transformation is a matrix transformation.

This means that for any linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ there is an $m \times n$ matrix A so that

$$T(v) = Av$$

for all v in \mathbb{R}^n .

The matrix for a linear transformation is called the **standard matrix**.

Linear transformations are matrix transformations

Theorem. Every linear transformation is a matrix transformation.

Given a linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ the standard matrix is:

$$A = \left(\begin{array}{c|c|c|c} | & | & \cdots & | \\ T(e_1) & T(e_2) & & T(e_n) \\ | & | & & | \end{array} \right)$$

Why? Notice that $Ae_i = T(e_i)$ for all i . Then it follows from linearity that $T(v) = Av$ for all v .

The identity

The **identity** linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is

$$T(v) = v$$

What is the standard matrix?

This standard matrix is called I_n or I .

Linear transformations are matrix transformations

Suppose $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is the function given by:

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x + y \\ y \\ x - y \end{pmatrix}$$

What is the standard matrix for T ?

Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of \mathbb{R}^2 that stretches by 2 in the x -direction and 3 in the y -direction, and then reflects over the line $y = x$.

Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of \mathbb{R}^2 that projects onto the y -axis and then rotates counterclockwise by $\pi/2$.

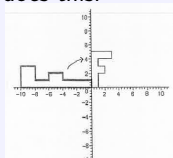
Linear transformations are matrix transformations

Find the standard matrix for the linear transformation of \mathbb{R}^3 that reflects through the xy -plane and then projects onto the yz -plane.

Discussion

Discussion Question

Find a matrix that does this.



▶ Transformation Challenge

Summary of Section 3.3

- A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **linear** if
 - ▶ $T(u + v) = T(u) + T(v)$ for all u, v in \mathbb{R}^n .
 - ▶ $T(cv) = cT(v)$ for all $v \in \mathbb{R}^n$ and c in \mathbb{R} .
- **Theorem.** Every linear transformation is a matrix transformation (and vice versa).
- The standard matrix for a linear transformation has its i th column equal to $T(e_i)$.

Typical Exam Questions Section 3.3

- Is the function $T : \mathbb{R} \rightarrow \mathbb{R}$ given by $T(x) = x + 1$ a linear transformation?
- Suppose that $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ is a linear transformation and that

$$T \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 3 \\ 1 \end{pmatrix} \quad \text{and} \quad T \begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 1 \end{pmatrix}$$

What is

$$T \begin{pmatrix} 1 \\ 0 \end{pmatrix}?$$

- Find the matrix for the linear transformation $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ that rotates about the z -axis by π and then scales by 2.
- Suppose $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is the function given by:

$$T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} z \\ 0 \\ x \end{pmatrix}$$

Is this a linear transformation? If so, what is the standard matrix for T ?

- Is the identity transformation one-to-one?