

Chapter 2

Review

Chapter 2 Review

Matrix Multiplication and Inverses

Products

$$AB \neq BA$$

$$T_{AB} = T_A \circ T_B$$

Inverses

- if $AB = BA = I$, then $B = A^{-1}$
- $T_A^{-1} = T_{A^{-1}}$
- $Ax = b \rightsquigarrow x = A^{-1}b$
- Find A^{-1} by row reducing $(A|I)$ to get $(I|A^{-1})$
- Another perspective: $E_k E_{k-1} \cdots E_2 E_1 A = I$, where each E_i is an elementary matrix. This implies that $E_k E_{k-1} \cdots E_2 E_1 = A^{-1}$.

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Invertible Matrix Theorem

Let A be an $n \times n$ matrix. The following are equivalent:

- A is invertible
- A can be reduced to I
- A has n pivots
- $\text{Nul}(A) = \{0\}$
- T_A is one-to-one
- T_A is onto
- $Ax = b$ is consistent for all b
- $\dim \text{Col}(A) = n$

etc ...

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LU Decompositions

Let $A = LU$, where L is lower triangular, U is in echelon form.

- Easy to solve for many b .
- Algorithm
 - ▶ Step 1. Solve $Ly = b$
 - ▶ Step 2. Solve $Ux = y$
- To find L and U , row reduce A to echelon form to obtain U , then use negative of row operations to obtain L . Be careful:
 - ▶ go column by column
 - ▶ only use lower row replacement

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Subspaces

- A **subspace** is a non-empty subset of \mathbb{R}^n closed under linear combinations.
- Two important subspaces are
 - ▶ $\text{Col}(A)$ = span of columns of A .
 - ▶ $\text{Nul}(A)$ = (solutions to $Ax = 0$).
- A **basis** for a subspace W is a set of lin. ind. vectors that spans W .
 - ▶ To find the B -coords of u , solve $Bx = u$
- The **dimension** of a subspace is the number of elements in the basis.
- Use row reduction to find a basis for $\text{Col}(A)$ or $\text{Nul}(A)$.
 - ▶ Pivot columns are used to identify the basis for $\text{Col}(A)$.
 - ▶ Parametric form is used to identify the basis for $\text{Nul}(A)$.

Note. $\text{Col}(A) = \text{range of } T_A$

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Rank Theorem Let A be an $m \times n$ matrix, then

$$\dim \operatorname{Col}(A) + \dim \operatorname{Nul}(A) = n.$$

Basis Theorem

Suppose V is a k -dimensional subspace of \mathbb{R}^n . Then

- Any k linearly independent vectors in V form a basis for V .
- Any k vectors in V that span V form a basis.

Midterm 2

Piazza Questions

Matrix Algebra

Solve for X :

$$(A - AX)^{-1} = X^{-1}B$$

Matrix Algebra

True/False.

$$(A + B)^2 = A^2 + 2AB = B^2$$

If A and B are invertible then $A + B$ is invertible.

If $Ax = 0$ has the trivial solution then A is invertible.

Elementary Matrices

Find a product of elementary matrices that equals

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$$

Areas and Determinants

Find the area of the triangle in \mathbb{R}^2 with vertices $(-5, 3)$, $(0, 5)$, and $(47, 24)$.

Let B be a ball of radius 1 in \mathbb{R}^3 . The volume of B is $4\pi/3$. Let

$$A = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 4 & 9 \\ 0 & 0 & 2 \end{pmatrix}$$

What is the volume of $T_A(B)$?

Inverses and Determinants

Find the matrix of cofactors for

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{pmatrix}$$

What is A^{-1} ?

Properties of Determinants

Suppose that A is a 5×5 matrix with determinant 3.

Is A invertible?

What is $\det(-A)$?

What is $\det(A^{-1})$?

What is $\det A^T$?

What is the determinant of the matrix obtained from A by replacing the first row with twice the first row plus the second row?

Bases and Coordinates

Let

$$b_1 = \begin{pmatrix} 1 \\ -2 \end{pmatrix} \text{ and } b_2 = \begin{pmatrix} -2 \\ 5 \end{pmatrix}$$

and $B = \{b_1, b_2\}$. Explain why B is a basis for \mathbb{R}^2 .

What is $[e_1]_B$? In other words, what are the B -coordinates of $e_1 = (1, 0)$?

Computing Determinants

Compute:

$$\det \begin{pmatrix} 1 & 0 & 1 \\ 2 & 0 & 1 \\ 2 & 1 & 1 \end{pmatrix}$$