

# Section 3.6

## The invertible matrix theorem

## Section 3.6 Outline

- The invertible matrix theorem

## The Invertible Matrix Theorem

Say  $A = n \times n$  matrix and  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the associated linear transformation. The following are equivalent.

- (1)  $A$  is invertible
- (2)  $T$  is invertible
- (3) The reduced row echelon form of  $A$  is  $I_n$
- (4)  $A$  has  $n$  pivots
- (5)  $Ax = 0$  has only  $0$  solution
- (6)  $\text{Nul}(A) = \{0\}$
- (7)  $\text{nullity}(A) = 0$
- (8) columns of  $A$  are linearly independent
- (9) columns of  $A$  form a basis for  $\mathbb{R}^n$
- (10)  $T$  is one-to-one
- (11)  $Ax = b$  is consistent for all  $b$  in  $\mathbb{R}^n$
- (12)  $Ax = b$  has a unique solution for all  $b$  in  $\mathbb{R}^n$
- (13) columns of  $A$  span  $\mathbb{R}^n$
- (14)  $\text{Col}(A) = \mathbb{R}^n$
- (15)  $\text{rank}(A) = n$
- (16)  $T$  is onto
- (17)  $A$  has a left inverse
- (18)  $A$  has a right inverse

## The Invertible Matrix Theorem

There are two kinds of square matrices, invertible and non-invertible matrices.

For invertible matrices, all of the conditions in the IMT hold. And for a non-invertible matrix, all of them fail to hold.

One way to think about the theorem is: there are lots of conditions equivalent to a matrix having a pivot in every row, and lots of conditions equivalent to a matrix having a pivot in every column, and when the matrix is a square, all of these many conditions become equivalent.

## Example

Determine whether  $A$  is invertible.  $A = \begin{pmatrix} 1 & 0 & -2 \\ 3 & 1 & -2 \\ -5 & -1 & 9 \end{pmatrix}$

It isn't necessary to find the inverse. Instead, we may use the Invertible Matrix Theorem by checking whether we can row reduce to obtain three pivot columns, or three pivot positions.

$$A = \begin{pmatrix} 1 & 0 & -2 \\ 3 & 1 & -2 \\ -5 & -1 & 9 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 4 \\ 0 & 1 & -1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 0 & -2 \\ 0 & 1 & 4 \\ 0 & 0 & 3 \end{pmatrix}$$

There are three pivot positions, so  $A$  is invertible by the IMT (statement c).

# The Invertible Matrix Theorem

## Poll

Which are true? Why?

- m) If  $A$  is invertible then the rows of  $A$  span  $\mathbb{R}^n$
- n) If  $Ax = b$  has exactly one solution for all  $b$  in  $\mathbb{R}^n$  then  $A$  is row equivalent to the identity.
- o) If  $A$  is invertible then  $A^2$  is invertible
- p) If  $A^2$  is invertible then  $A$  is invertible

## Some sample Yes/No questions

In all questions, suppose that  $A$  is an  $n \times n$  matrix and that  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the associated linear transformation.

(1) Suppose that the reduced row echelon form of  $A$  does not have any zero rows. Must it be true that  $Ax = b$  is consistent for all  $b$  in  $\mathbb{R}^n$ ?

YES

NO

(2) Suppose that  $T$  is one-to-one. Is it possible that the columns of  $A$  add up to zero?

YES

NO

(3) Suppose that  $Ax = e_1$  is not consistent. Is it possible that  $T$  is onto?

YES

NO

## Summary of Section 3.6

- Say  $A = n \times n$  matrix and  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is the associated linear transformation. The following are equivalent.
  - (1)  $A$  is invertible
  - (2)  $T$  is invertible
  - (3) The reduced row echelon form of  $A$  is  $I_n$
  - (4) etc.