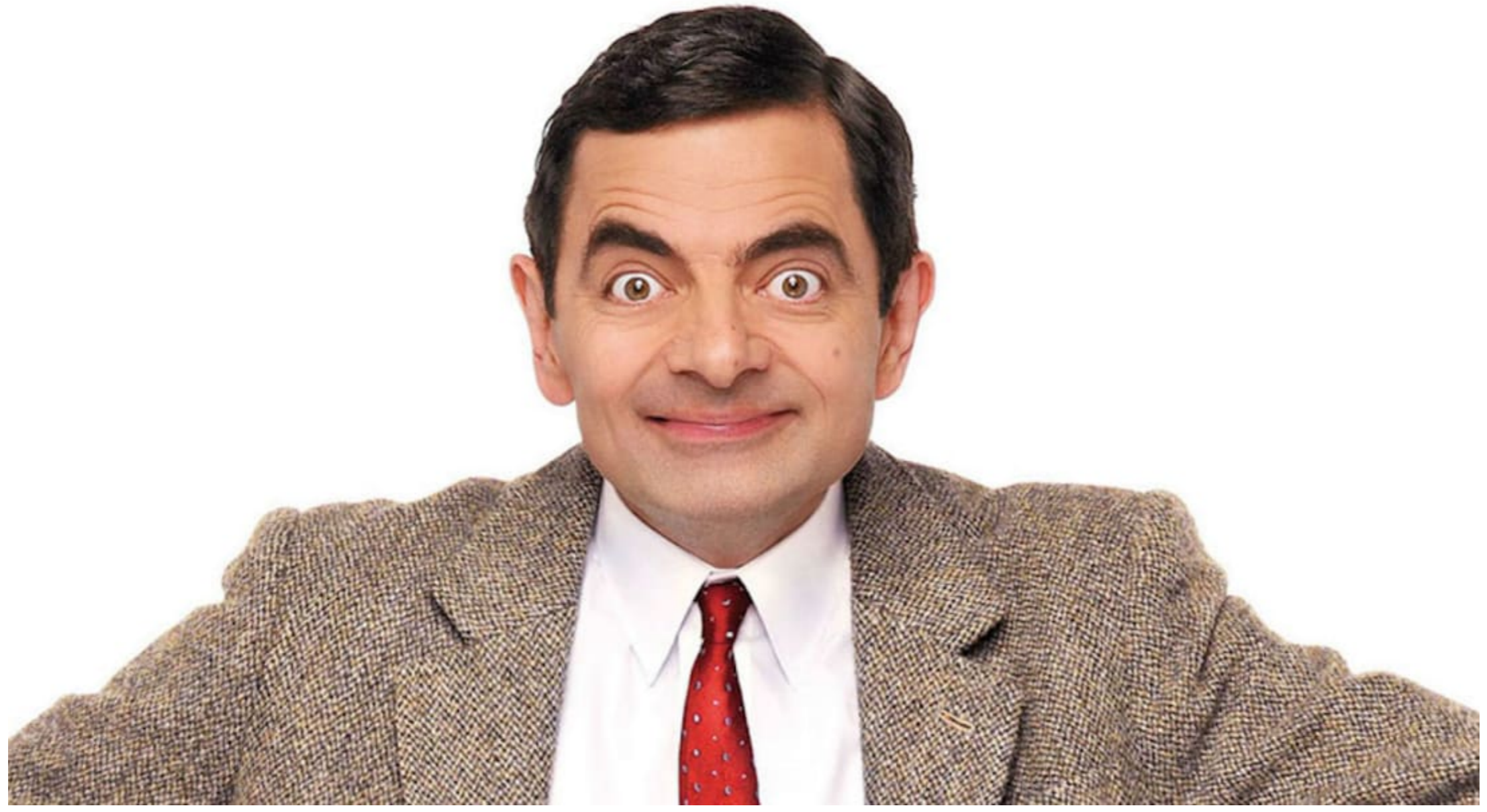


Announcements Feb 19

- Midterm 2 on **March 6** **3.2 & 3.3**
- WeBWorK ~~2.7, 2.9, 3.1~~ due Thursday
- Mid-semester evaluation under Quizzes on Canvas (due today)
- **My office hours Monday 3-4 and Wed 2-3** in Skiles 234
- **Pop-up office hours Wed 11-11:30 this week** in Skiles 234
- TA office hours in Skiles 230 (you can go to any of these!)
 - ▶ Isabella Thu 2-3
 - ▶ Kyle Thu 1-3
 - ▶ Kalen Mon/Wed 1-1:50
 - ▶ Sidhanth Tue 10:45-11:45
- PLUS sessions Mon/Wed 6-7 LLC West with Miguel
- Supplemental problems and practice exams on the master web site
- **Quiz on 3.2, 3.3 on Fri**







Section 3.4

Matrix Multiplication

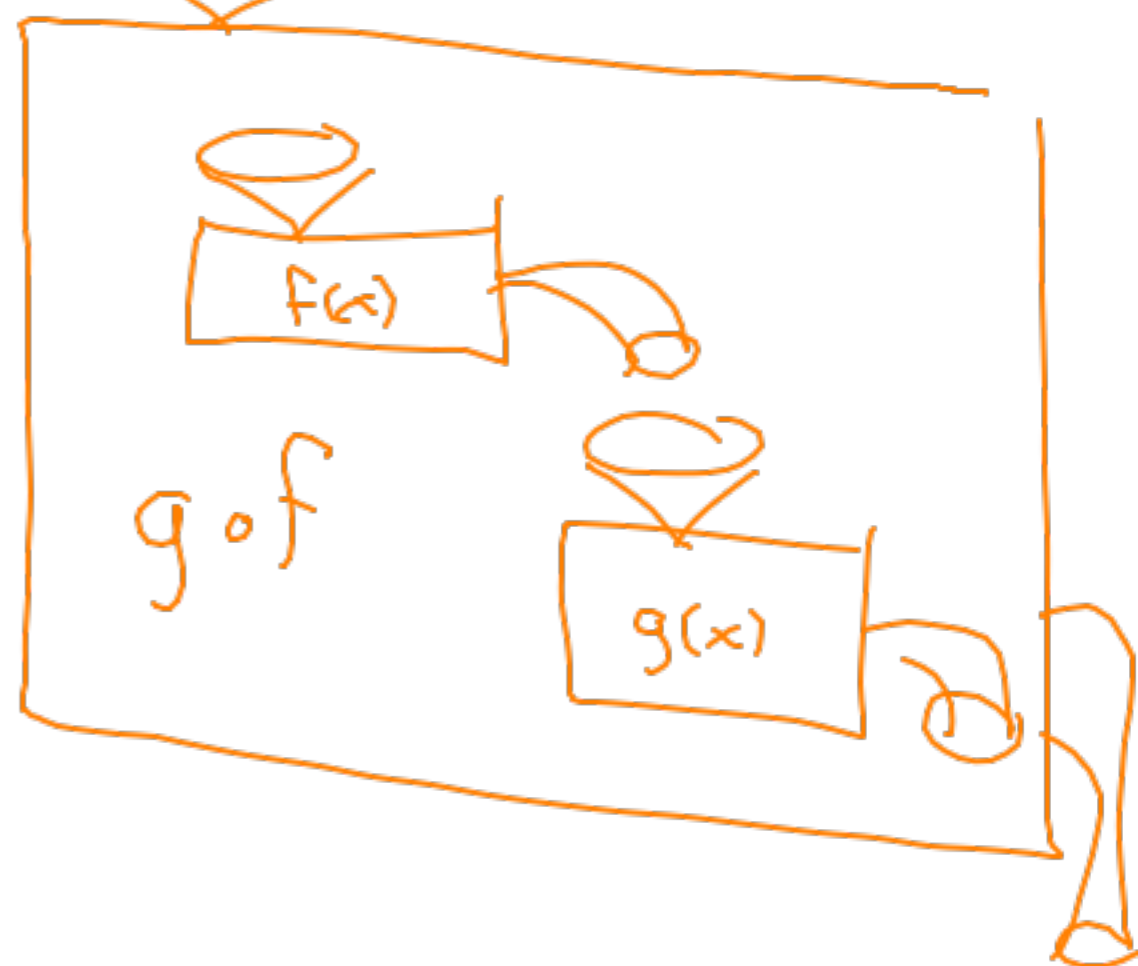
Section 3.4 Outline

- Understand composition of linear transformations
- Learn how to multiply matrices
- Learn the connection between these two things

Composition: $g \circ f(x) = g(f(x))$

Example: $f(x) = x + 1$
 $g(x) = x^2$

$$\begin{aligned} \rightarrow g \circ f(x) &= (x+1)^2 \\ f \circ g(x) &= x^2 + 1 \end{aligned}$$



Function composition

Remember from calculus that if f and g are functions then the composition $f \circ g$ is a new function defined as follows:

$$f \circ g(x) = f(g(x))$$

In words: first apply g , then f .

Example: $f(x) = x^2$ and $g(x) = x + 1$.

Note that $f \circ g$ is usually different from $g \circ f$.

Composition of linear transformations

We can do the same thing with linear transformations $T: \mathbb{R}^m \rightarrow \mathbb{R}^p$ and $U: \mathbb{R}^n \rightarrow \mathbb{R}^m$ and make the composition $T \circ U$.

Notice that both have an m . Why?

What are the domain and codomain for $T \circ U$?

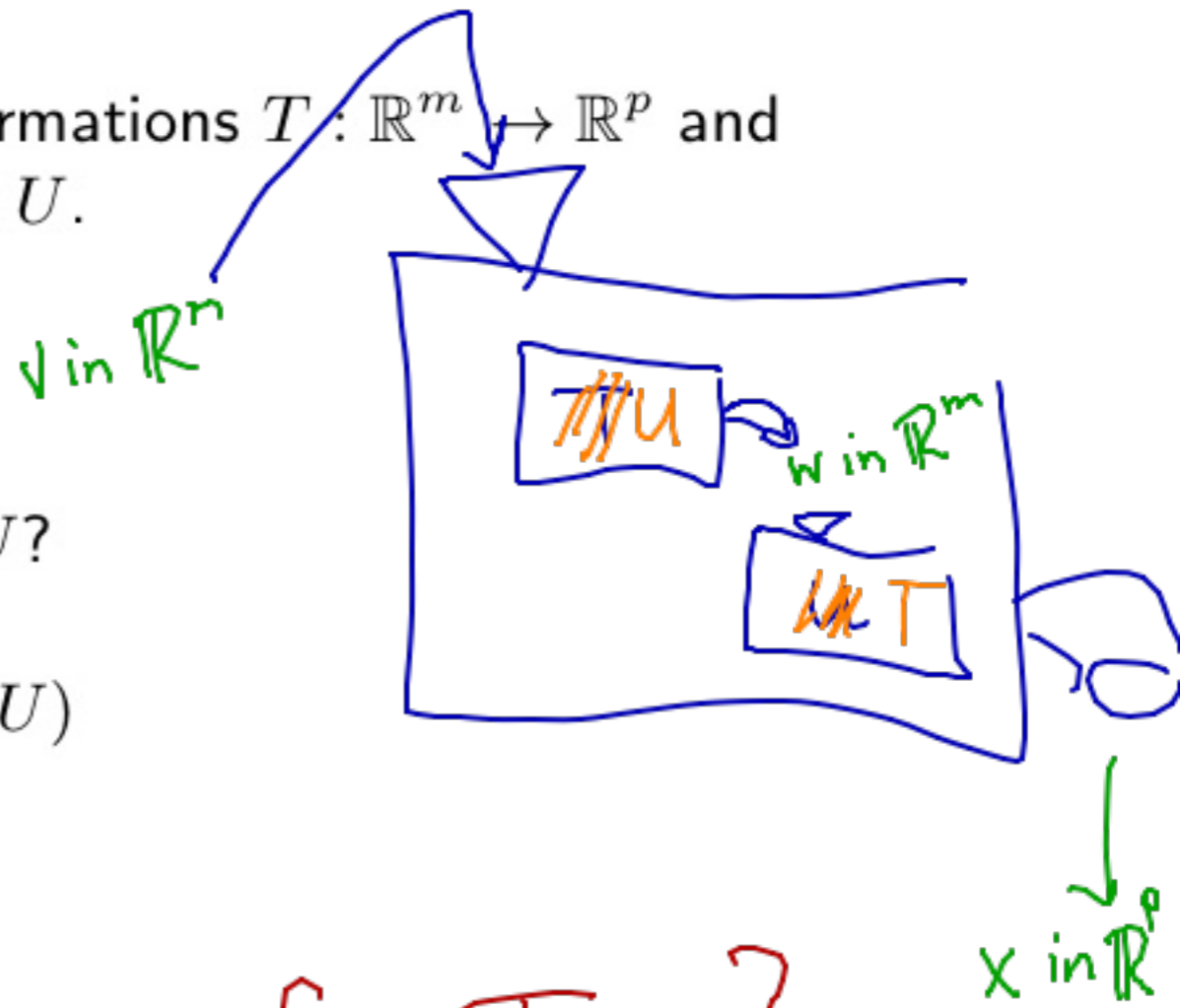
Associative property: $(S \circ T) \circ U = S \circ (T \circ U)$

Why?

What is the matrix for $T \circ U$?

We know: $p \times n$

range contained in range of T



Composition of linear transformations

Example. T = projection to y -axis and
 U = reflection about $y = x$ in \mathbb{R}^2

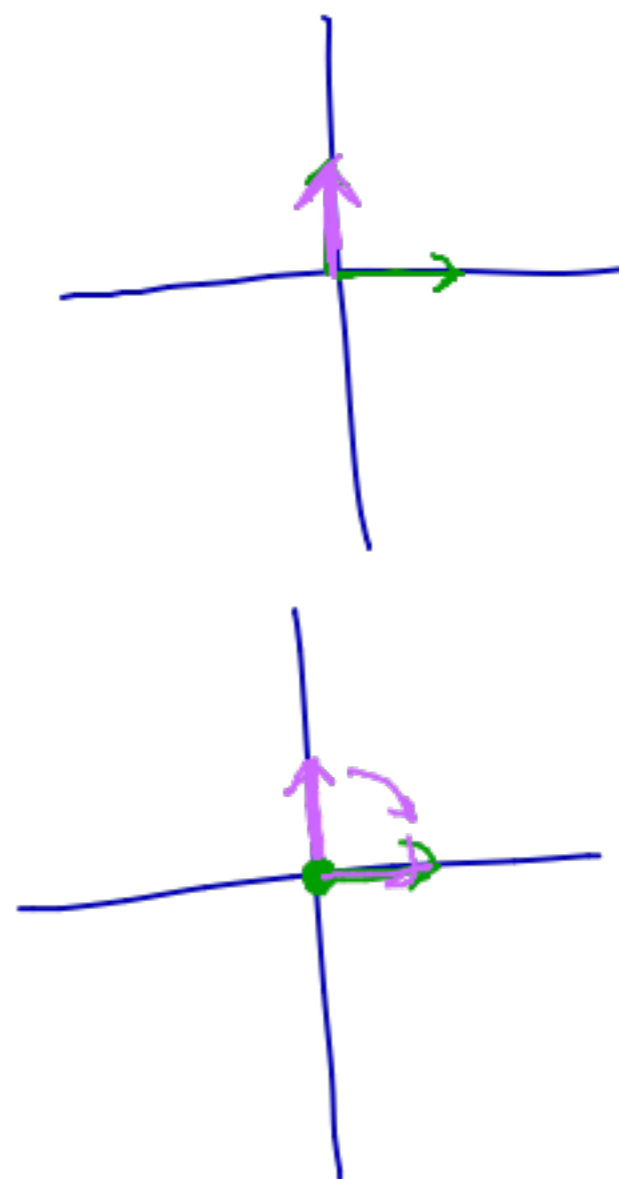
$$\begin{aligned} T: \mathbb{R}^2 &\rightarrow \mathbb{R}^2 \\ U: \mathbb{R}^2 &\rightarrow \mathbb{R}^2 \end{aligned}$$

What is the standard matrix for $T \circ U$?

What about $U \circ T$?

$$T \circ U \iff \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$U \circ T \iff \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$



Matrix Multiplication

And now for something completely different (not really!)

Suppose A is an $m \times n$ matrix. We write a_{ij} or A_{ij} for the ij th entry.

If A is $m \times n$ and B is $n \times p$, then AB is $m \times p$ and

$$(AB)_{ij} = r_i \cdot b_j$$

where r_i is the i th row of A , and b_j is the j th column of B .

Or: the j th column of AB is A times the j th column of B .

Multiply these matrices (both ways):

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} \begin{pmatrix} 0 & -2 \\ 1 & -1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 8 & -4 \\ 17 & -13 \end{pmatrix}$$

2×3 3×2 2×2

Matrix Multiplication and Linear Transformations

As above, the **composition** $T \circ U$ means: do U then do T

Fact. Suppose that A and B are the standard matrices for the linear transformations $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $U : \mathbb{R}^p \rightarrow \mathbb{R}^n$. The standard matrix for $T \circ U$ is AB .

Why?

$$(T \circ U)(v) = T(U(v)) = T(Bv) = A(Bv)$$

So we need to check that $A(Bv) = (AB)v$. Enough to do this for $v = e_i$. In this case Bv is the i th column of B . So the left-hand side is A times the i th column of B . The right-hand side is the i th column of AB which we already said was A times the i th column of B . It works!

Matrix Multiplication and Linear Transformations

Fact. Suppose that A and B are the standard matrices for the linear transformations $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $U : \mathbb{R}^p \rightarrow \mathbb{R}^n$. The standard matrix for $T \circ U$ is AB .

Example. $T =$ projection to y -axis and $U =$ reflection about $y = x$ in \mathbb{R}^2

What is the standard matrix for $T \circ U$?

$$\text{Matrix for } T : \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\text{Matrix for } U : \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\text{Matrix for } T \circ U = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$U \circ T = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

Linear transformations are matrix transformations

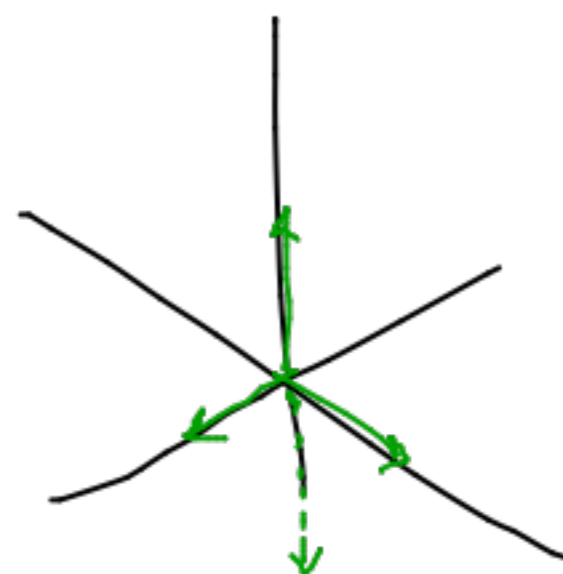
Find the standard matrix for the linear transformation of \mathbb{R}^3 that reflects through the xy -plane and then projects onto the yz -plane.

T

U

$$T \leftrightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$U \leftrightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$



$$U \circ T \leftrightarrow \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$T \circ U \leftrightarrow \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

Discussion Question

Are there nonzero matrices A and B with $AB = 0$?

1. Yes
2. No

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Properties of Matrix Multiplication

- $A(BC) = (AB)C$ b/c composition of L.T.'s \leftrightarrow mult of mat's
- $A(B + C) = AB + AC$
- $(B + C)A = BA + CA$
- $r(AB) = (rA)B = A(rB)$ r in \mathbb{R} (scalar)
- ~~$(AB)^T = B^T A^T$~~
- $I_m A = A = A I_n$, where I_k is the $k \times k$ identity matrix.

Multiplication is associative because function composition is (this would be hard to check from the definition!).

Warning!

- AB is not always equal to BA
- $AB = AC$ does not mean that $B = C$
- $AB = 0$ does not mean that A or B is 0

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \mathbf{0}$$

Sums and Scalar Multiples

Same as for vectors: component-wise, so matrices must be same size to add.

$$A + B = B + A$$

$$(A + B) + C = A + (B + C)$$

$$r(A + B) = rA + rB$$

$$(r + s)A = rA + sA$$

$$(rs)A = r(sA)$$

$$A + 0 = A$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

(We can define linear transformations $T + U$ and cT , and so all of the above facts are also facts about linear transformations.)

Summary of Section 3.4

- Composition: $(T \circ U)(v) = T(U(v))$ (do U then T)
- Matrix multiplication: $(AB)_{ij} = r_i \cdot b_j$
- Matrix multiplication: the i th column of AB is $A(b_i)$
- Suppose that A and B are the standard matrices for the linear transformations $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $U : \mathbb{R}^p \rightarrow \mathbb{R}^n$. The standard matrix for $T \circ U$ is AB .
- **Warning!**
 - ▶ AB is not always equal to BA
 - ▶ $AB = AC$ does not mean that $B = C$
 - ▶ $AB = 0$ does not mean that A or B is 0

Section 3.5 Outline

- The definition of a matrix inverse
- How to find a matrix inverse
- Inverses for linear transformations

$$7x = 35$$
$$7^{-1} \cdot 7x = 7^{-1} \cdot 35$$
$$1 \cdot x = 5$$

Inverses

To solve

$$Ax = b$$

we might want to “divide both sides by A ”.

We will make sense of this...

Inverses

$A = n \times n$ matrix.

A is **invertible** if there is a matrix B with

$$AB = BA = I_n$$

B is called the **inverse** of A and is written A^{-1}

Example:

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}^{-1} = \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

The 2×2 Case

Let $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$. Then $\det(A) = ad - bc$ is the **determinant** of A .

Fact. If $\det(A) \neq 0$ then A is invertible and $A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$.

If $\det(A) = 0$ then A is not invertible.

$$\begin{pmatrix} 5 & 10 \\ 7 & 14 \end{pmatrix} = 5 \cdot 14 - 7 \cdot 10 = 0$$

not invertible!

Example. $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}^{-1} = -\frac{1}{2} \begin{pmatrix} 4 & -2 \\ -3 & 1 \end{pmatrix}$.

$$-\frac{1}{2} \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} 4 & -2 \\ -3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

Solving Linear Systems via Inverses

Fact. If A is invertible, then $Ax = b$ has exactly one solution:

$$x = A^{-1}b.$$

Solve

$$2x + 3y + 2z = 1$$

$$x + 3z = 1$$

$$2x + 2y + 3z = 1$$

Using

$$\begin{pmatrix} 2 & 3 & 2 \\ 1 & 0 & 3 \\ 2 & 2 & 3 \end{pmatrix}^{-1} = \begin{pmatrix} -6 & -5 & 9 \\ 3 & 2 & -4 \\ 2 & 2 & -3 \end{pmatrix}$$

Solving Linear Systems via Inverses

What if we change b ?

$$2x + 3y + 2z = 1$$

$$x + 3z = 0$$

$$2x + 2y + 3z = 1$$

Using

$$\begin{pmatrix} 2 & 3 & 2 \\ 1 & 0 & 3 \\ 2 & 2 & 3 \end{pmatrix}^{-1} = \begin{pmatrix} -6 & -5 & 9 \\ 3 & 2 & -4 \\ 2 & 2 & -3 \end{pmatrix}$$

So finding the inverse is essentially the same as solving all $Ax = b$ equations at once (fixed A , varying b).