

Announcements Mar 4

- Midterm 2 on **Friday**
- WeBWorK 3.4, 3.5, and 3.6 due Thursday
- TA office hours in Skiles 230 (you can go to any of these!)
 - ▶ Isabella Thu 2-3
 - ▶ Kyle Thu 1-3
 - ▶ Kalen Mon/Wed 1-1:50
 - ▶ Sidhanth Tue 10:45-11:45
- Review sessions
 - ▶ Kalen 7 pm Thu online
 - ▶ Sidhanth 7 pm tonite
- PLUS session with Miguel tonight 5-7
- Supplemental problems and practice exams on the master web site

Review for Midterm 2

Section 2.6 Summary

- A **subspace** of \mathbb{R}^n is a subset V with:
 1. The zero vector is in V .
 2. If u and v are in V , then $u + v$ is also in V .
 3. If u is in V and c is in \mathbb{R} , then $cu \in V$.
 - Two important subspaces: **Nul(A)** and **Col(A)**
 - Find a spanning set for Nul(A) by solving $Ax = 0$ in vector parametric form
 - Find a spanning set for Col(A) by taking pivot columns of A (not reduced A)
 - Four things are the same: subspaces, spans, planes through 0, null spaces
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Let V be the subset of \mathbb{R}^3 consisting of the x -axis, the y -axis, and the z -axis. Which properties of a subspace does V fail?

Find a spanning set for the plane in \mathbb{R}^3 defined by $x + y - 2z = 0$.

Section 2.7 Summary

- A **basis** for a subspace V is a set of vectors $\{v_1, v_2, \dots, v_k\}$ such that
 1. $V = \text{Span}\{v_1, \dots, v_k\}$
 2. v_1, \dots, v_k are linearly independent
 - The number of vectors in a basis for a subspace is the dimension.
 - Find a basis for $\text{Nul}(A)$ by solving $Ax = 0$ in vector parametric form
 - Find a basis for $\text{Col}(A)$ by taking pivot columns of A (not reduced A)
 - **Basis Theorem**. Suppose V is a k -dimensional subspace of \mathbb{R}^n . Then
 - ▶ Any k linearly independent vectors in V form a basis for V .
 - ▶ Any k vectors in V that span V form a basis.
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Find a basis $\{u, v, w\}$ for \mathbb{R}^3 where no vector has a zero entry.

Section 2.9 Summary

- Rank-Nullity Theorem. $\text{rank}(A) + \dim \text{Nul}(A) = \#\text{cols}(A)$
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Let A be an 4×6 nonzero matrix and suppose the columns of A are all the same. What is $\dim \text{Nul}(A)$?

Section 3.1 Summary

- If A is an $m \times n$ matrix, then the associated matrix transformation T is given by $T(v) = Av$. This is a function with domain \mathbb{R}^n and codomain \mathbb{R}^m and range $\text{Col}(A)$.
 - If A is $n \times n$ then T does something to \mathbb{R}^n ; basic examples: reflection, projection, scaling, shear, rotation
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Find a matrix A so that the range of the matrix transformation $T(v) = Av$ is the line $y = 2x$ in \mathbb{R}^2 .

Summary of Section 3.2

- $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **one-to-one** if each b in \mathbb{R}^m is the output for at most one v in \mathbb{R}^n .
- **Theorem.** Suppose $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a matrix transformation with matrix A . Then the following are all equivalent:
 - ▶ T is one-to-one
 - ▶ the columns of A are
 - ▶ $Ax = 0$ has
 - ▶ A has a pivot
 - ▶ the range has dimension n
- $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **onto** if the range of T equals the codomain \mathbb{R}^m , that is, each b in \mathbb{R}^m is the output for at least one input v in \mathbb{R}^n .
- **Theorem.** Suppose $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a matrix transformation with matrix A . Then the following are all equivalent:
 - ▶ T is onto
 - ▶ the columns of A
 - ▶ A has a pivot
 - ▶ $Ax = b$ is consistent
 - ▶ the range of T has dimension m

Let A be an 5×5 matrix. Suppose that $\dim \text{Nul}(A) = 0$. Must it be true that $Ax = e_1$ is consistent?

Summary of Section 3.3

- A function $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **linear** if
 - ▶ $T(u + v) = T(u) + T(v)$ for all u, v in \mathbb{R}^n .
 - ▶ $T(cv) = cT(v)$ for all $v \in \mathbb{R}^n$ and c in \mathbb{R} .
 - **Theorem.** Every linear transformation is a matrix transformation (and vice versa).
 - The standard matrix for a linear transformation has its i th column equal to $T(e_i)$.
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Find the standard matrix for the linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ that reflects over the line $y = -x$ and then rotates counterclockwise by $\pi/2$.

Summary of Section 3.4

- Composition: $(T \circ U)(v) = T(U(v))$ (do U then T)
- Matrix multiplication: $(AB)_{ij} = r_i \cdot b_j$
- Matrix multiplication: the i th column of AB is $A(b_i)$
- The standard matrix for a composition of linear transformations is the product of the standard matrices.
- **Warning!**
 - ▶ AB is not always equal to BA
 - ▶ $AB = AC$ does not mean that $B = C$
 - ▶ $AB = 0$ does not mean that A or B is 0

Find a 2×2 matrix A , not equal to I , with $A^4 = I$.

Summary of Section 3.5

- A is **invertible** if there is a matrix B (called the inverse) with

$$AB = BA = I_n$$

- For a 2×2 matrix A we have that A is invertible exactly when $\det(A) \neq 0$ and in this case

$$A^{-1} = \frac{1}{\det(A)} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

- If A is invertible, then $Ax = b$ has exactly one solution: $x = A^{-1}b$.
 - $(A^{-1})^{-1} = A$ and $(AB)^{-1} = B^{-1}A^{-1}$
 - Recipe for finding inverse: row reduce $(A | I_n)$.
 - Invertible linear transformations correspond to invertible matrices.
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Find the inverse of the matrix

$$\begin{pmatrix} 1 & 0 & h \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Summary of Section 3.6

- Say $A = n \times n$ matrix and $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is the associated linear transformation. The following are equivalent.
 - (1) A is invertible
 - (2) T is invertible
 - (3) The reduced row echelon form of A is I_n
 - (4) etc.
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In all questions, suppose that A is an $n \times n$ matrix and that $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is the associated linear transformation.

(1) Suppose that the reduced row echelon form of A does not have any zero rows. Must it be true that $Ax = b$ is consistent for all b in \mathbb{R}^n ?

YES

NO

(2) Suppose that T is one-to-one. Is it possible that the columns of A add up to zero?

YES

NO

(3) Suppose that $Ax = e_1$ is not consistent. Is it possible that T is onto?

YES

NO

Important terms

- subspace
- column space
- null space
- basis
- dimension
- one-to-one
- onto
- linear transformation
- inverse
- Rank theorem

Good luck!

