Goal for today: coord free description of tangent spaces.

We'll show

$$T_{p} X \cong (M/M^{2})^{*} \cong (m/m^{2})^{*}$$

 $M \subseteq k[x_{1},...,x_{n}]$
 $m \subseteq k(x_{1},...,x_{n})$
max ideals at p :
 $M = (x_{1}-P_{1},...,x_{n}-P_{n})$
Fins that vanish at p

Cotangent spaces $T_p^*V = dual \text{ of } T_pV$ = $\{linear T_PV \rightarrow k\}$ = "(inear forms" Notation: gekEx1,..., Xn] dpg = diff. of g at p. e.g. $g(x,y) = \chi^2 + \chi y + \chi$ $dg = (2\chi + y + 1) \frac{d}{d\chi} + \chi \frac{d}{dy}$ $d_0g = \frac{d}{d\chi} \cdot \epsilon (k^n)^*$

Prop. Same X. Differentiation induces Prop. Let $X = Z(f_1, \dots, f_m) \in \mathbb{A}^n$ lustin surj $M \longrightarrow T_p^* V$ pex gek[x] R. Smith ~ deg is lin form on TeX. with kernel M². Pf. Setup. WLOG p=0. If To show well-def. WLOG TPV = < x1,..., Xr> Say G1, G2 & K[X1,..., Xn] 100. 9. (change of coords) \Rightarrow G₁-G₂ = \sum hifi hie I(X) Let $\widetilde{M} = (X_1, ..., X_n) \in k[X_1, ..., X_n]$ $\Rightarrow d_p(G_1-G_2) = \Sigma(d_ph_i)f_i(p)$ Its image in KEXJ is M. product + hilp)(de fi)) O by defn TrV defined = ○ □ so that this form evals to O on it.

Prop. Same X. Differentiation induces
surj
$$M \rightarrow Tp^* X$$

with Kennel M^2 . So: $Tp^* X = Ml_N$
PF. Setup. WLOG $P = 0$.
WLOG $Tp X = \langle x_1, ..., x_r \rangle$
(change of coords)
Let $\tilde{M} = (x_1, ..., x_n)$
Its image in K[X] is M .
Surjectivity: let $L = Zci x_i^* \in Tp^* X$
Then $L = Zci x_i$
has $dL = L$

Kernel: Say gEM, dog=OETp*X & g is image of GEM So doG = O on To X (first Prop) Then $d_0G = \sum \lambda_j (d_0f_j)$ (by defn of TpX) Let $\bar{G} = G - \sum \lambda_j f_j$ Then \overline{G} still maps to g in k[X]. But do E = O on To K ⇒ const & lin. terms of G vanish. $\Rightarrow \overline{G} \in \widetilde{M}^2 \Rightarrow g \in M^2 \square$

Moving the * R = ring, $M \subseteq R$ max ideal. $\sim \mathbf{R} \cdot \mathbf{M} \subseteq \mathbf{M}$, $\mathbf{R} \cdot \mathbf{M}^2 \subseteq \mathbf{M}^2$ So M, M/m² modules over R Also, mult by M on M/M2 is O map. So M/m² is R/M-module C field! i.e. M/m² is vect sp. over R/M So $T_PV = (M/M^2)^*$ makes sense

 $(M/M^2)^*$ is called Zariski tangent sp. Differentials Prop. f: X -> Y morphism of aav's pe X $\rightarrow f_* : T_P X \rightarrow T_{f(P)} Y$ $PF. f_* : key] \rightarrow key]$ prein of M is N=maxideal For f(p) = fins vanish@f(p) $S_{\circ} N/N^2 \longrightarrow M/M^2 \square$

Coord free descr. of differential Prop. X S / irred. fe kEXJ Then F - F(p) & M. and def = image of f-f(p) in $M/M^2 = T_p^* V$ Pf. Subtracting flp) kills const term. Modding by M² kills good & higher terms. 400¹.

Example $\chi = Z(\chi^3 - \gamma^2) \subseteq M^2$ At p=(1,1) can see dim $M/M^2 = 1$: $M = (\chi - 1, \gamma - 1) \chi^{3}$ $\longrightarrow M^2 = (\chi^2 - 2\chi + 1, (\chi - 1)(\eta - 1), \eta^2 - 2\eta + 1)$ $\rightarrow y - 1 = (x^{3+1})/2 - 1$ $= (\chi(2\chi-1)+1)/2 - 1$ $= (2x^2 - x + 1)/2 - 1$ = (3x - 1)/2 - 1 $= 3_{1/2}(\chi - 1)$ At p = (0,0) can see dim $M/M^2 = 2$: $M = (x, y), M^2 = (x^2, xy, y^2)$ $\rightarrow M/M^2 = \{ax+by\}$

Projective varieties Ox,p= {flg e K(X) : g(p) + 0} me fige Ox, p sit. f(p)=0 max ideal. Lemma. X, M, m, p as above. $M|_{M^2} \cong m/_{m^2}$ $\frac{PF}{M} = 0.$ Inclusion $M \longrightarrow m$ Induces injection $M|_{M^2} \longrightarrow m/m^2$

Surj Let Flg & m/m2 so g(0) = 0 $\rightarrow fl_{g(0)} - fl_{g}$ = $f('|g|_{0} - '|g) \in m^{2}$ So f|g|o| = f|g in m/m^2 in $M \subseteq k[X]$ Cor 1. $f: X \to Y$ rot. $\longrightarrow f_*: T_P X \to T_{f(P)} Y.$ Cor2. X, Y birat -> dim X = dim Y Back to dim Thm X = A irred $\dim X = \operatorname{trdeg}_{K} K(X)$. Milne Also: trdeg k(X) = dim k[X]. IF. IF it's true for hypersurfaces, true for all X since every Hulek X is birat. equiv to hypersurf. (Noether norm).

For hypersurfaces: We proved dim=n-1 so suff. to show tr deg=n-1 $\chi = Z(f) \subseteq IA^{n}$ firred. $\sim k[X] = k[X_1, ..., X_n]/(f)$ WLOG F USES X1 $k(X) = k(x^{5},...,x^{n})[x_{1}](t)$ transc. basis.

HEISUKE HIRONAKA "Resolution of singularities of an algebraic variety over a field of characteristic Annals of Math.



§9. The notion of J-stability.

§ 10. The existence of a J-stable regular r-frame and a J-stable standard base. Chapter IV. THE FUNDAMENTAL THEOREMS AND THEIR PROOFS.

Localization of resolution data and resolution problems.

- \$2. Preparation on resolution data $(R^{N,n}, U)$.
- \$3. Proofs of the implications (A) and (B).
- §4. Proofs of the implications (C) and (D).

Introduction

Let X be complex-(resp. real-)analytic space, i.e., an analytic C-(resp. **R**-)space in the sense defined in §1 of Chapter 0. We ask if there exists a morphism of complex-(resp. real-)analytic spaces, say $f: \tilde{X} \to X$, such that:

(1) \widetilde{X} is a complex-(resp. real-)analytic manifold, i.e., a non-singular complex-(resp. real-)analytic space,

(2) if V is the open subspace of X which consists of the simple points of X, then f⁻¹(V) is an open dense subspace of X and f induces an isomorphism of complex-(resp. real-)analytic manifolds: f⁻¹(V) [≈] → V, and

(3) f is proper, i.e., the preimage by f of any compact subset of X is compact in \tilde{X} .

This is the problem which we call the resolution of singularities in the category of complex-(resp. real-)analytic spaces, or more specifically, the resolution of singularities of the given complex-(resp. real-)analytic space X. If X is a reduced complex-analytic space, then the open subspace V is dense in X and therefore the condition (2) implies that f is a modification. (The term 'reduced' means that the structural sheaf of local rings has no nilpotent elements.) It should be noted, however, that V is not always dense if X is a reduced real-analytic space. So far as the resolution of singularities is concerned, we are particularly interested in the case of reduced complex-(resp. real-)analytic spaces. As for the general case in which X may not be reduced, we have a better formulation of the problem in terms of normal flatness. (See Definition 1, § 4, Ch. 0.)

The most significant result of this work is the solution of the above problem for the case in which X has an algebraic structure; that is to say, X is covered by a finite number of coordinate neighborhoods, each of

