APPICATIONS OF TT ,

Browner's Fixed Pt thm
Every
$$h: D^2 \rightarrow D^2$$
 has a
fixed pt.

Last time:
$$f:(X, x_0) \rightarrow (Y, y_0)$$

 $\sim f_{x}: \pi_1(X, x_0) \rightarrow \pi_1(Y, y_0)$
Prop i: $A \rightarrow X$ inclusion
 $r: X \rightarrow A$ retraction
 $\Rightarrow i_{x}$ injective. X
PF. $roi = id$
 $\Rightarrow Gain = id$

Jan 26 TF of BFPT Suppose h: $D^2 \rightarrow D^2$ has no fixed pt. Then there is a retraction $D^2 \rightarrow S^1$



• Ham sandwich thm. • If S²=union of 3 closed sets, one has a pair of artip. pts. Fundamental Thr of Alg Every nonconst. poly with coeff's in C has a root in C.

Idea. If ox(t) is a loop in (& p(z) is a poly with no roots on X(t) ~ loop in S' by projecting. $\alpha(t)$ p $\rho \circ \alpha(t)$ projection: X ~ ×/IIXII.

For proof: modify & and p to get a homotopy from degree n loop in St to const. loop, The forther. Say $p(z) = z^n + a_1 z^{n-1} + \dots + a_n$ Assume no roots Let $p_s(z) = \overline{z}^n + s(a_1 \overline{z}^{n-1} + \dots + a_n)$ Let &r(t) = circle of radius r in C. Let $R > |a, | + \dots + |an| + 1$ (Jaim. Ps(Z) has no roots on XR deg n 100p r=R each pt is a s' loopin S' s=1 loop. □

Last time:

Fact. f homeo -> fx isom. Prop. π(S")=1, n>1 ₽. Sⁿ - pt ≅ Rⁿ (stereographic proj). Suffices to show : any loop is homotopic to one that is not surjective.



Prop. R² # Rⁿ n>2 $Pf. \quad \mathbb{R}^n \sim pt^n \cong S^{n-1} \times \mathbb{R}$ (polar coords) $\mathfrak{N}_{i}(\mathbb{R}^{n}-p!)\cong\mathfrak{N}_{i}(S^{n-i}\times\mathbb{R})$ Fact \cong \Re , $(S^{n-1}) \times \Re$, (\mathbb{R}) ≅ m, (Sⁿ⁻¹) $\cong \left\{ \begin{array}{l} \mathbb{Z} & n=2\\ 1 & n \neq 2 \end{array} \right.$ Apply Fact. and the "any"

By

Prop. If $\varphi:(\chi,\chi_0) \longrightarrow (\chi,\chi_0)$ homeq. Proof of this last fact: then que is \cong . It's the change of basept isomorphism from last time. IF. Let Y be homotopy inverse i.e. yo q ~ id. isomorphism. H1 (X0) HIOK Remains to show: (40 (P) = Id = id. Ht(X0) Or: Ht: X -> X homotopy Hys & Ho = id Then $(H_1)_*$: $\mathcal{N}_1(X, x_0) \longrightarrow \mathcal{N}_1(X, H_1(x_0))$ R is an isomorphism.